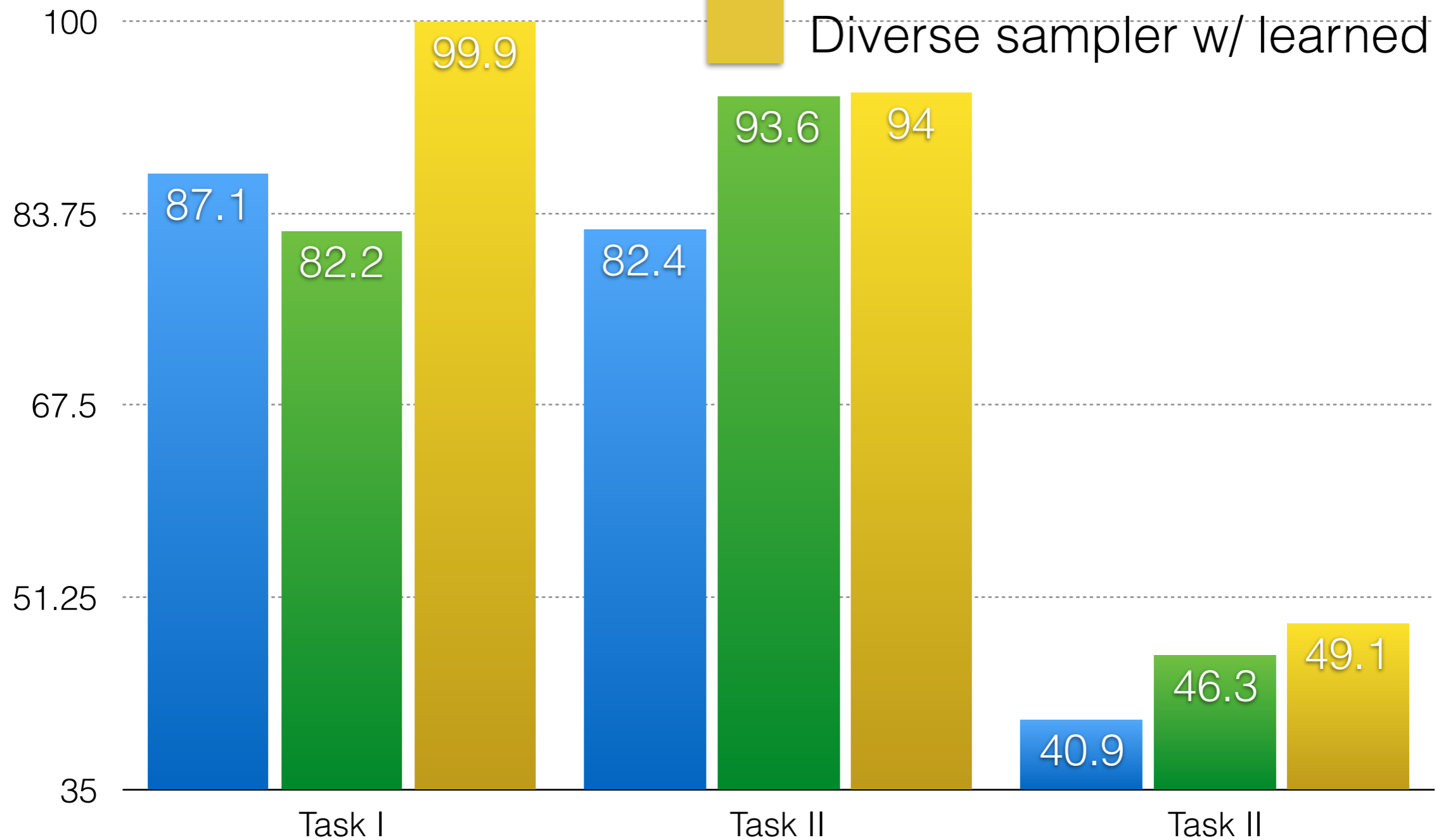


# Diverse sampler is sample efficient

Success rate  
in 0.02 s (Task I)  
in 6 s (Task II/III)

- Adaptive rejection sampler
- Diverse sampler w/ given kernel
- Diverse sampler w/ learned kernel



# Flexible integration with TAMP

- Pre-existing operators
  - dispense coffee
  - pick up, place object
  - move robot
  - stir
  - dump spoon
- Learned operators
  - push
  - pour
  - scoop

