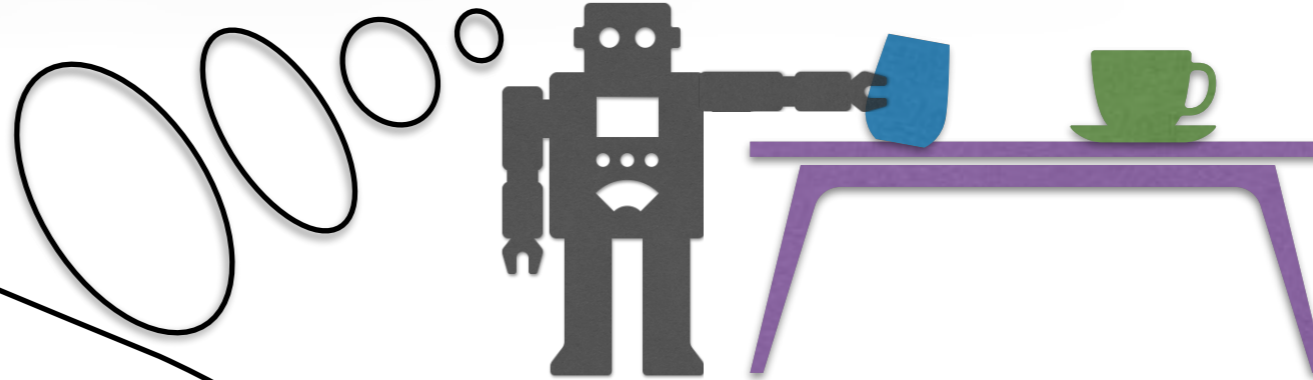


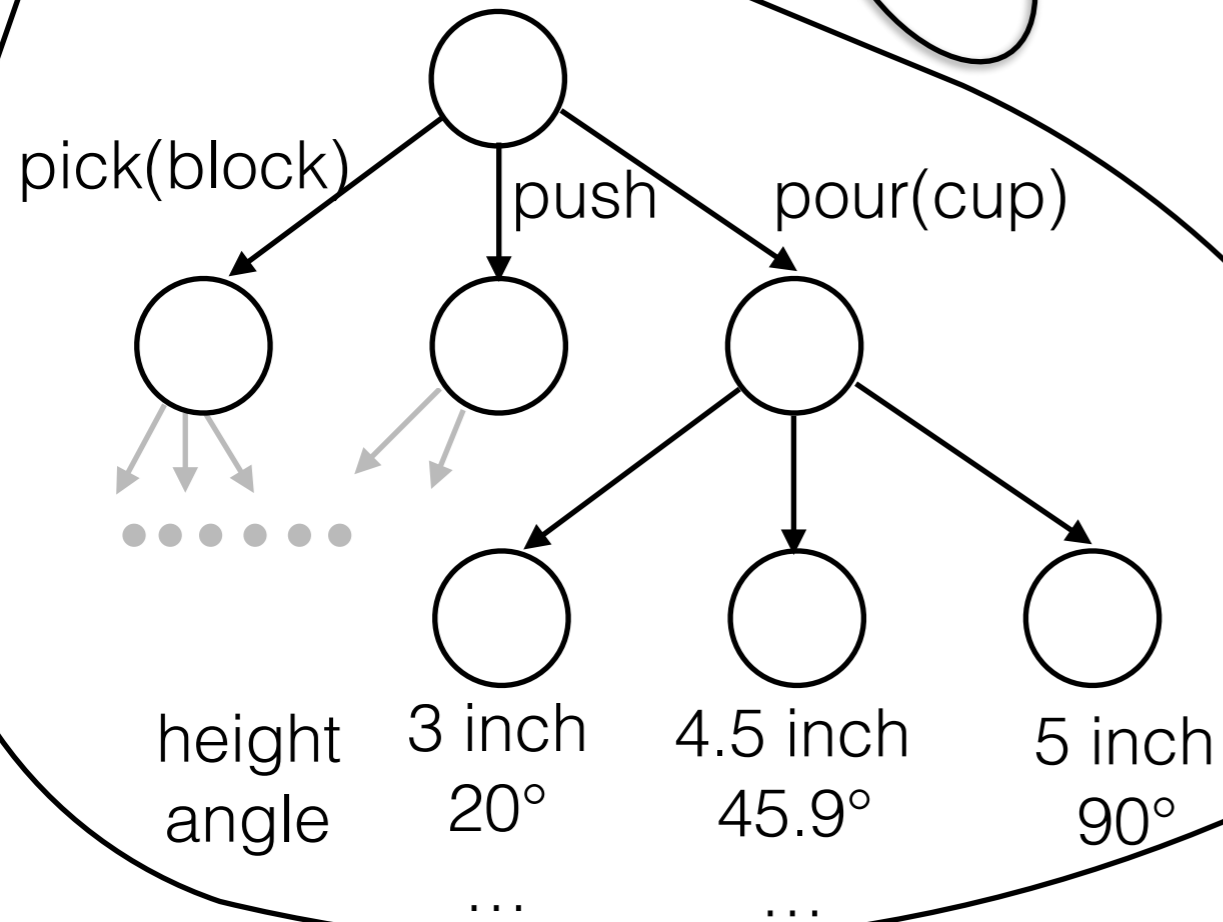
# Enable robots to solve high-level long-horizon problems



# A typical task and motion planner



current state



## Key subroutines

- Sample continuous action parameters
- Tree search on both discrete and continuous variables