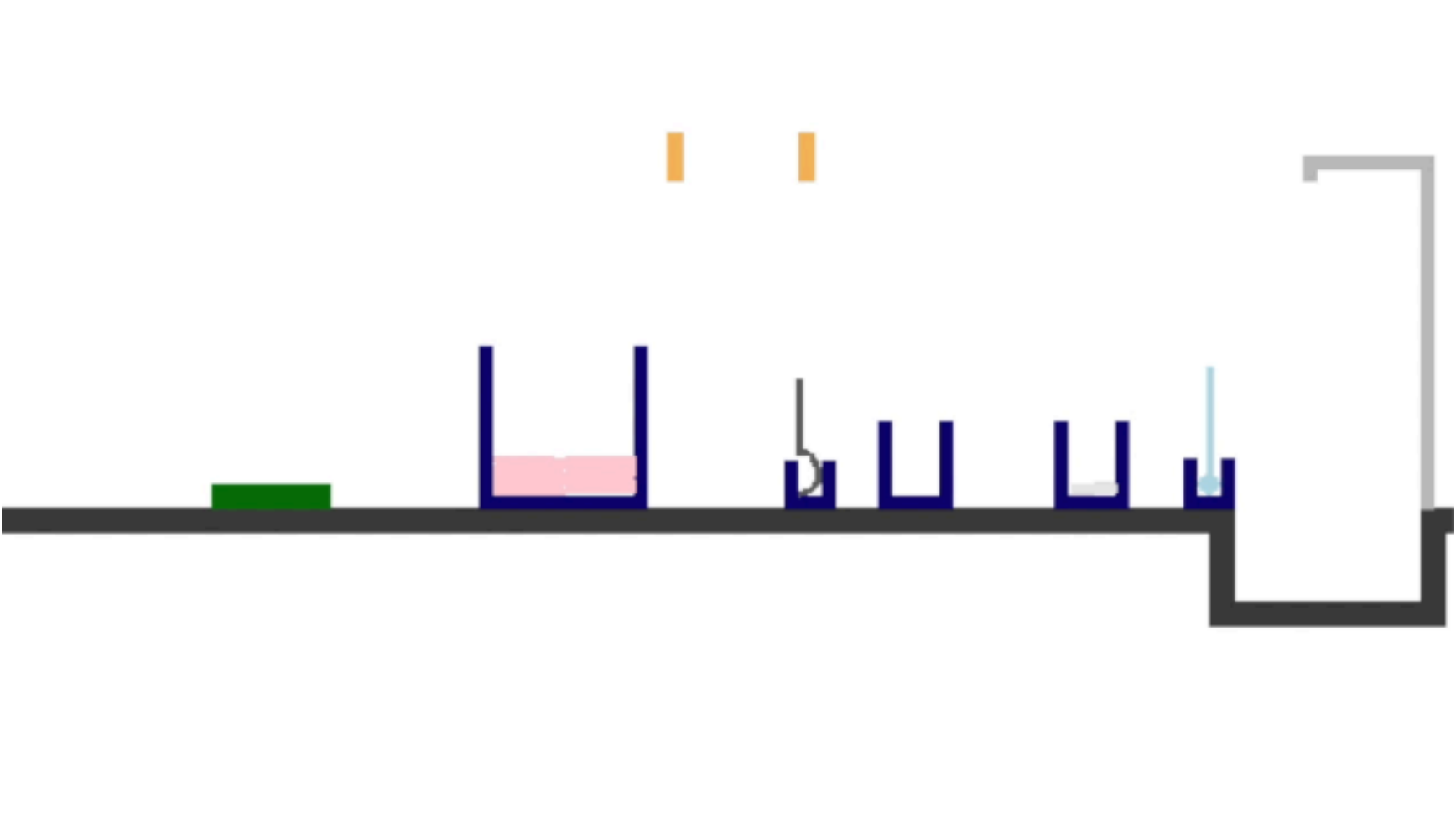
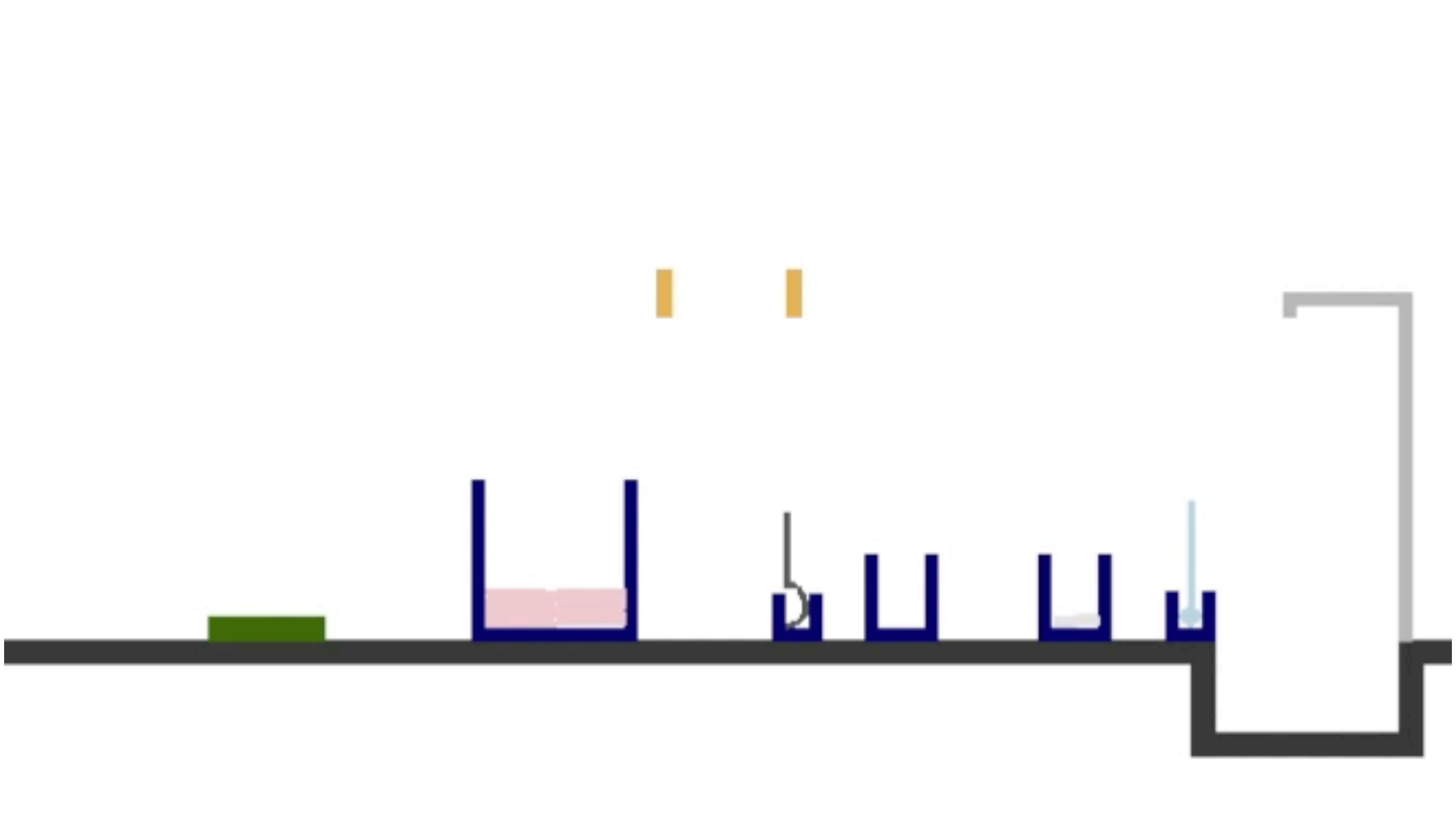
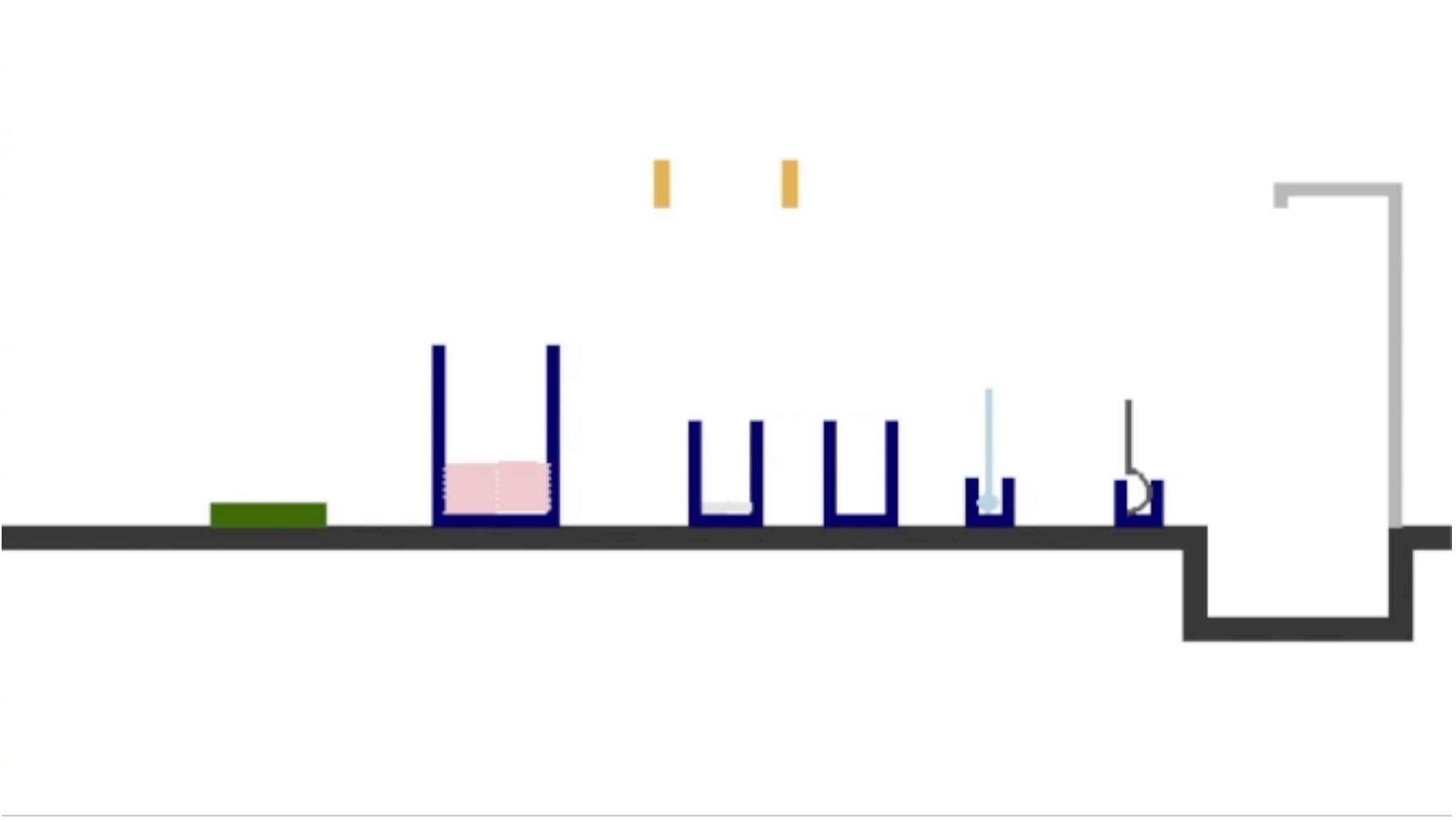




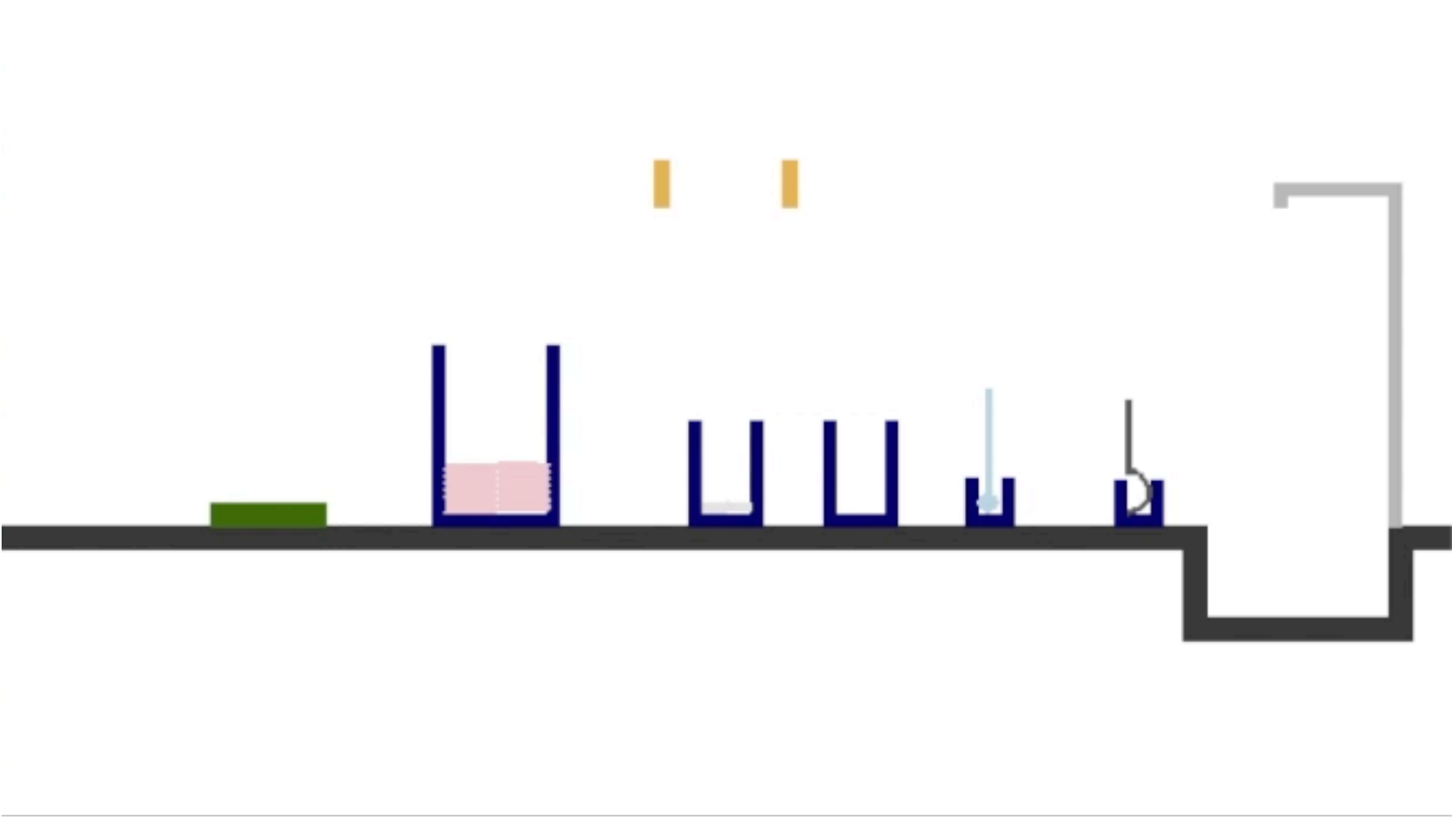
- Generalize over different layout of objects
- Generalize over different shapes of objects
- Resulting plans can be different when solving the same problem

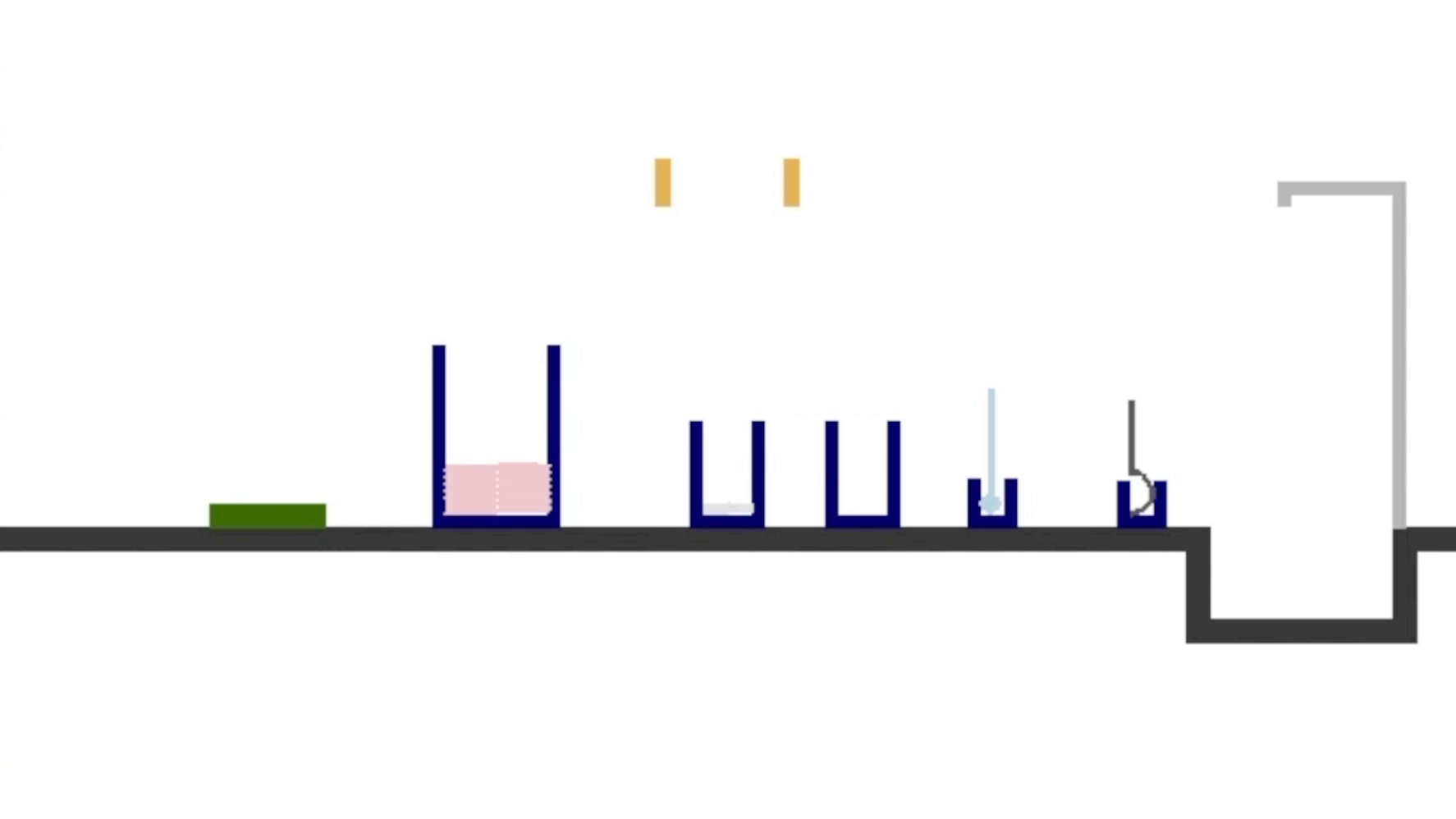




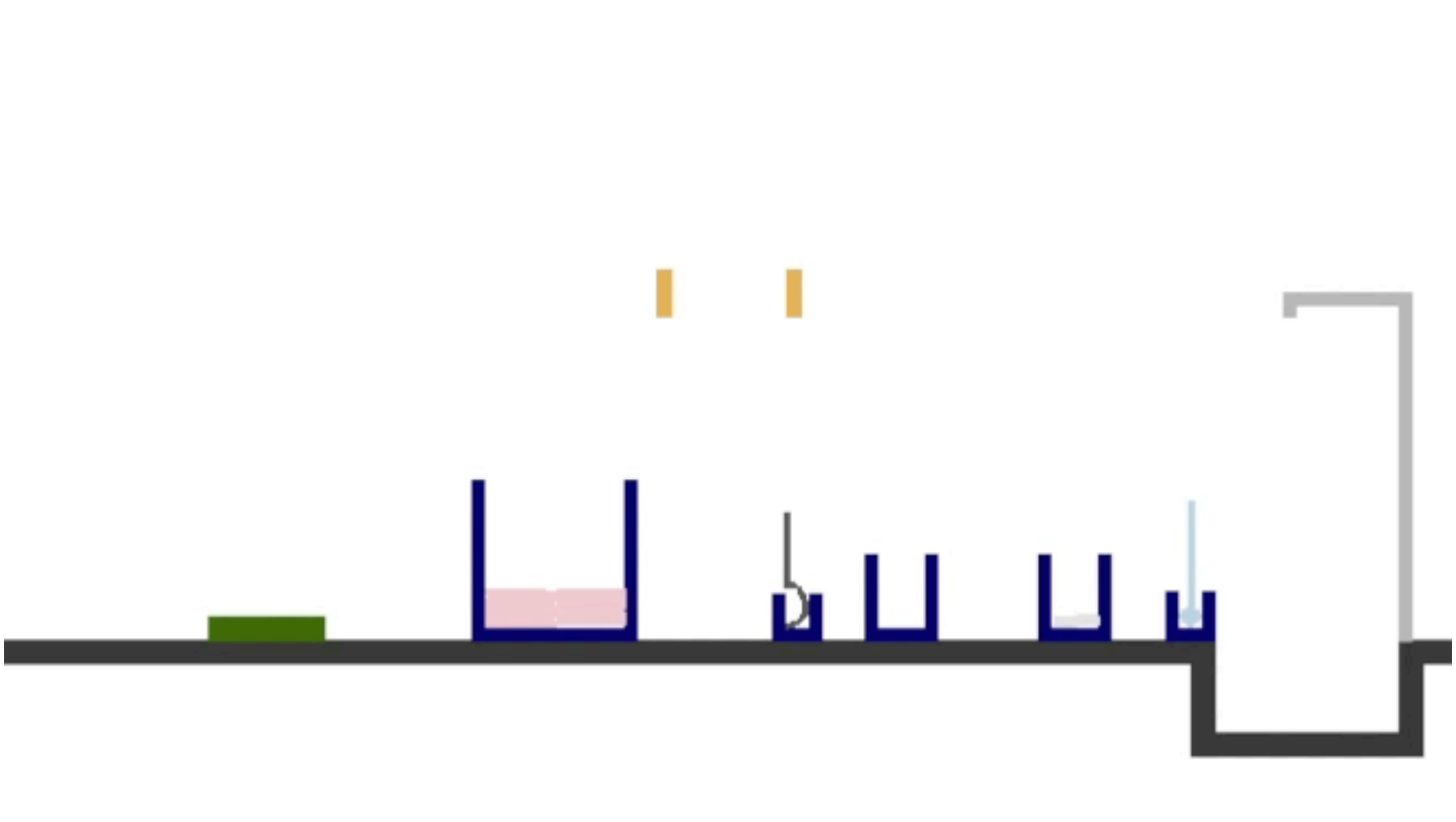


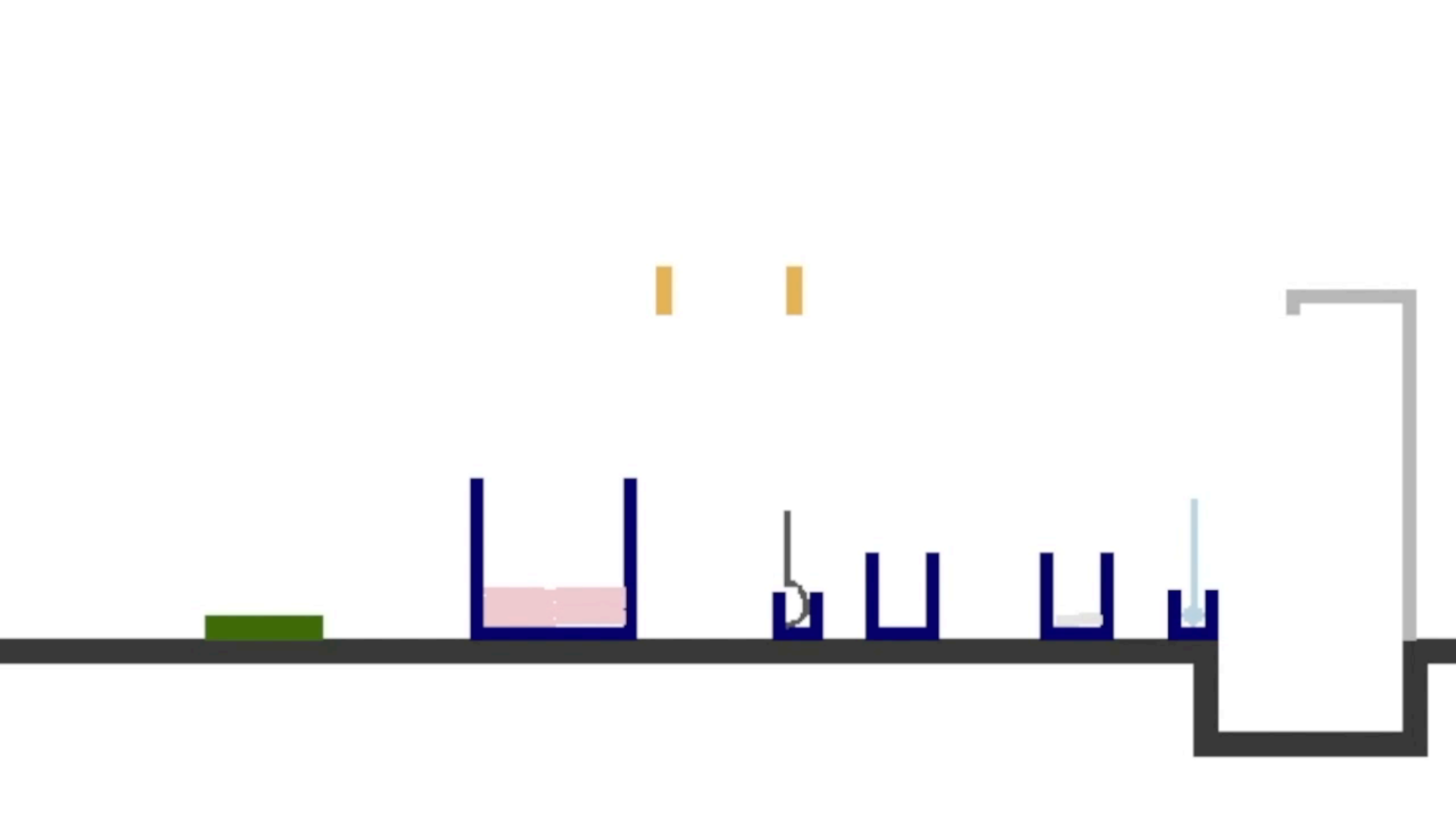
Flexible integration with TAMM

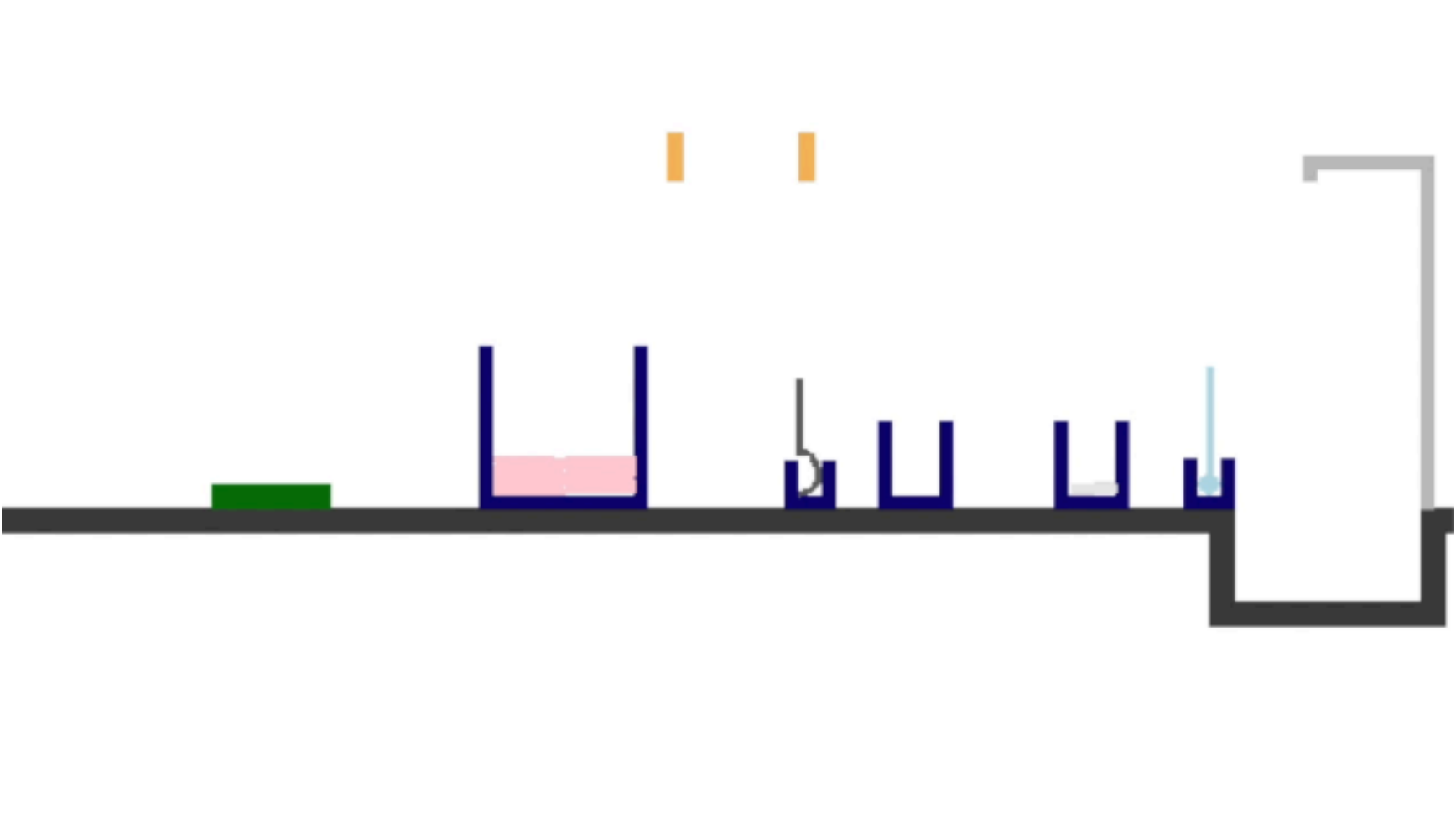


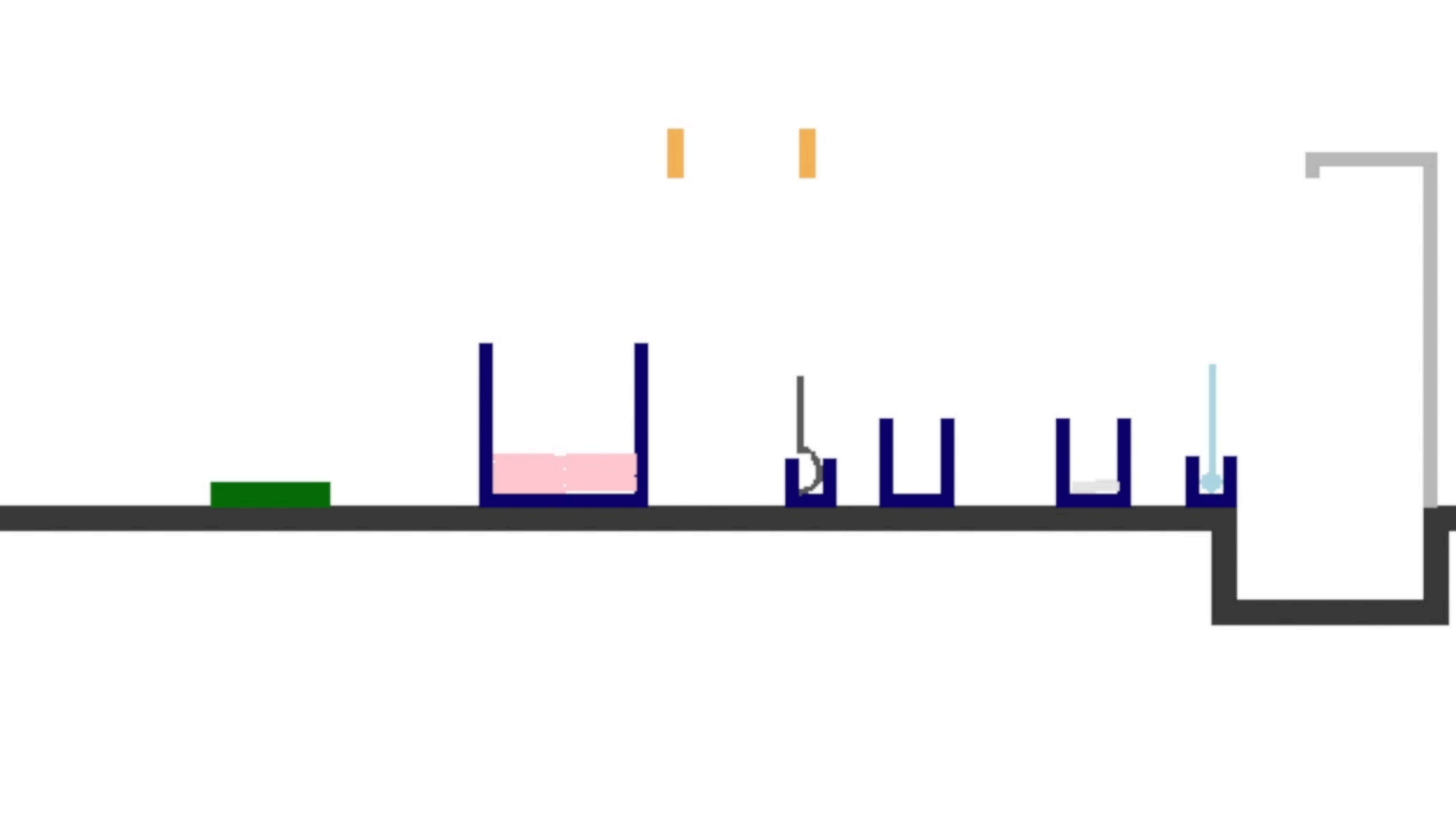






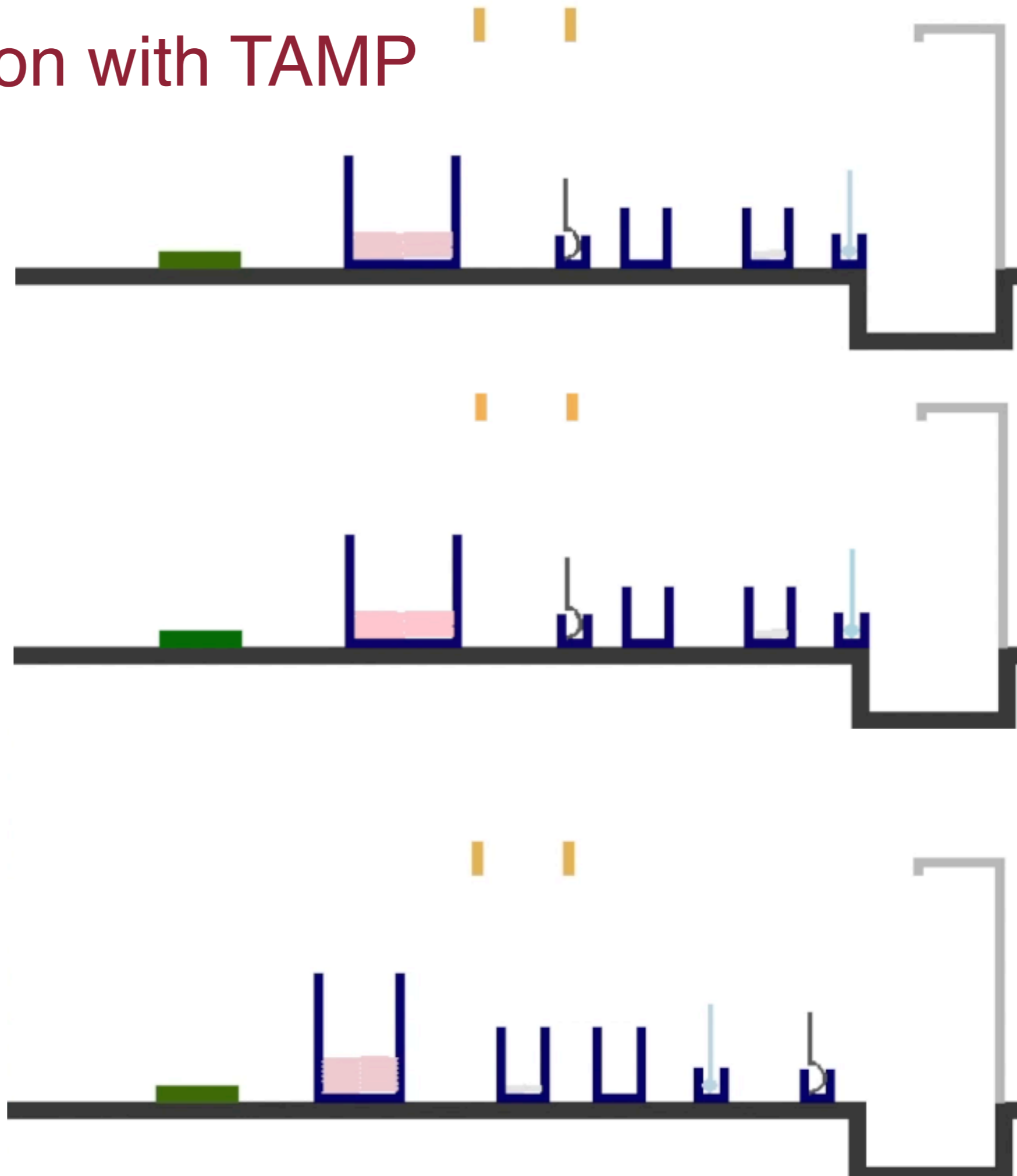






# Flexible integration with TAMP

- Generalize over different layout of objects
- Generalize over different shapes of objects
- Resulting plans can be different when solving the same problem



# Implementation on the real robot

