

# Optimization as Estimation with Gaussian Processes in Bandit Settings

Zi Wang, Bolei Zhou, Stefanie Jegelka

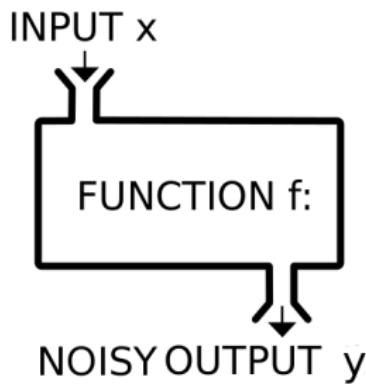


*ziw, bzhou, stefje@csail.mit.edu*

May 9, 2016

# Black-box function optimization in the bandit setting

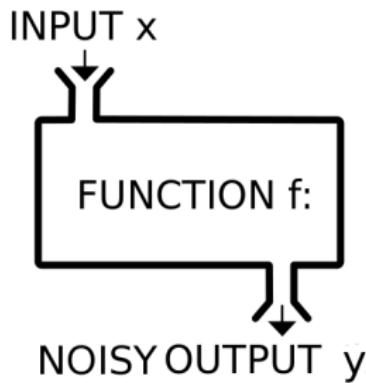
maximize <sub>$x \in \mathcal{X}$</sub>   $f(x)$



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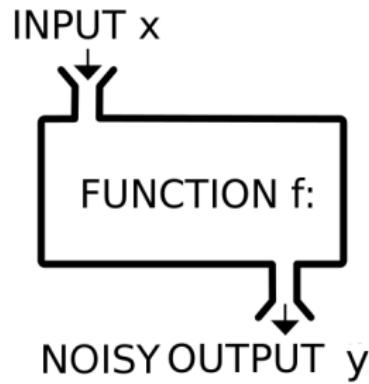
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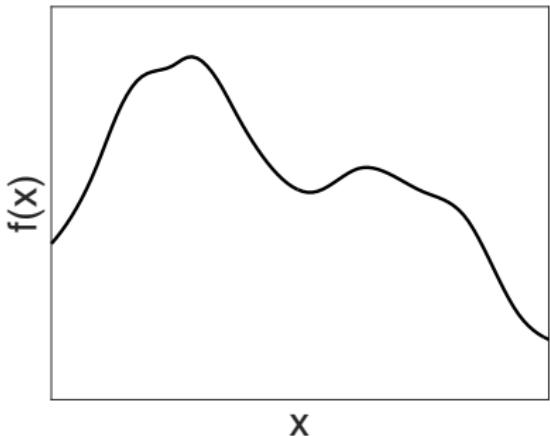
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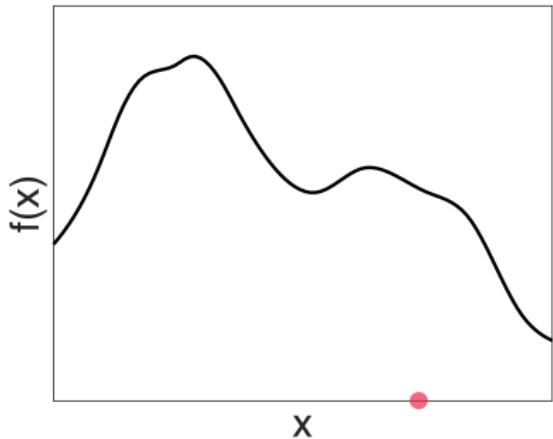


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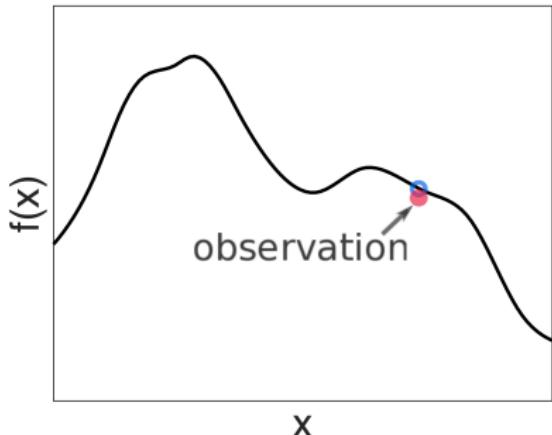
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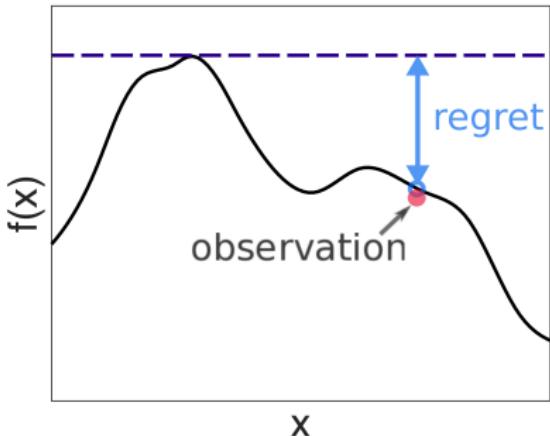
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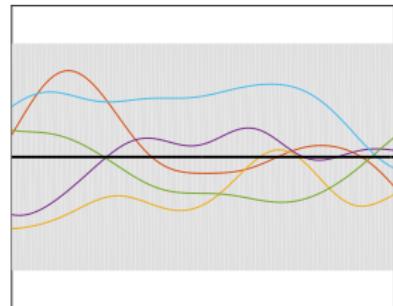
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**Goal:** Minimize cumulative regret  $R_T = \sum_{t=1}^T (\max_{\mathbf{x} \in \mathfrak{X}} f(\mathbf{x}) - f(\mathbf{x}_t))$

# Gaussian process optimization

Assume  $f \sim GP(\mu, k)$ .



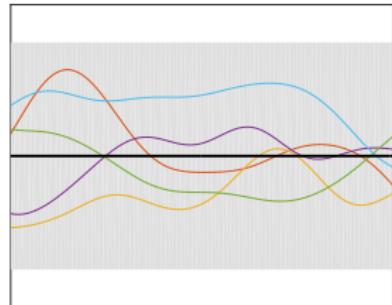
Prior distribution

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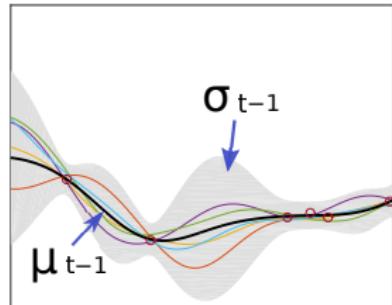
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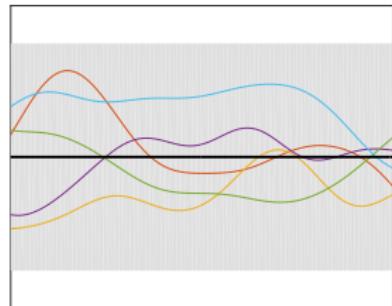
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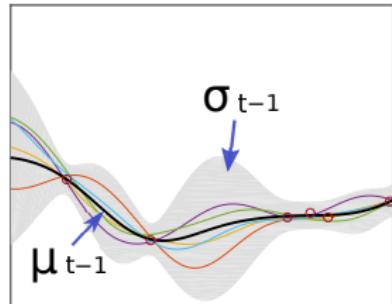
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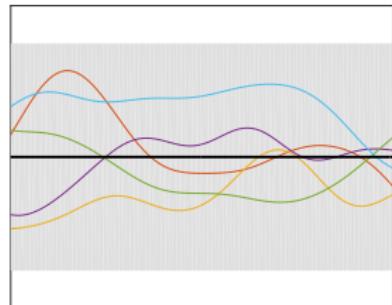
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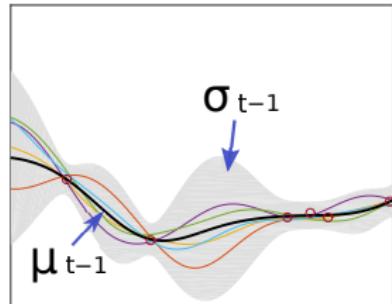
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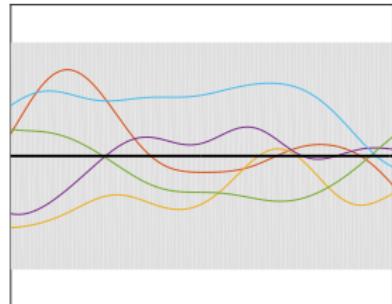
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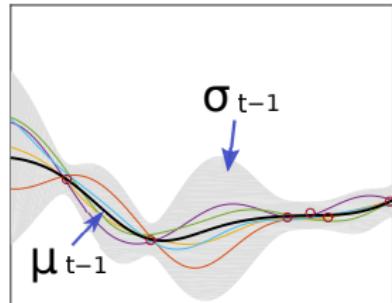
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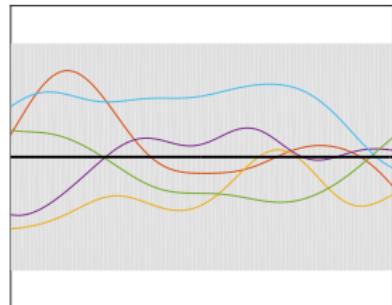
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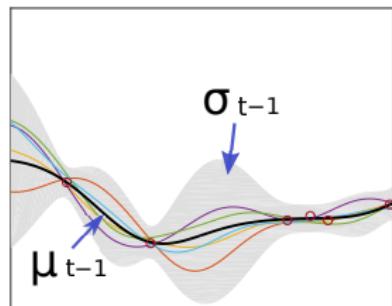
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Examples:



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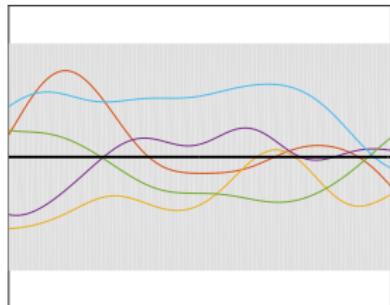
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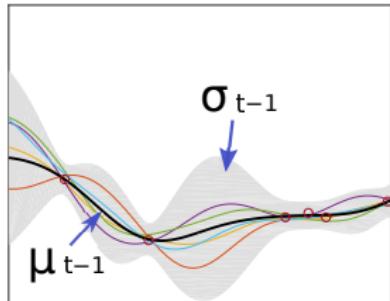
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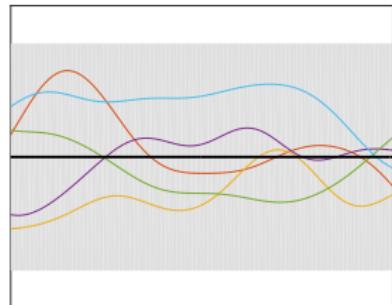
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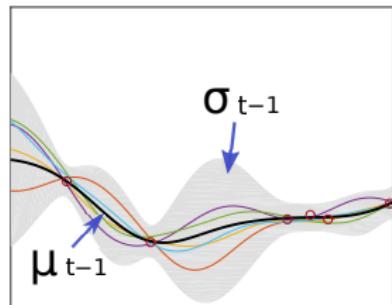
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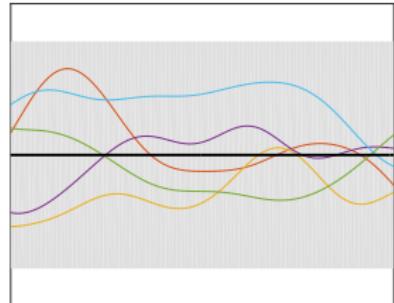
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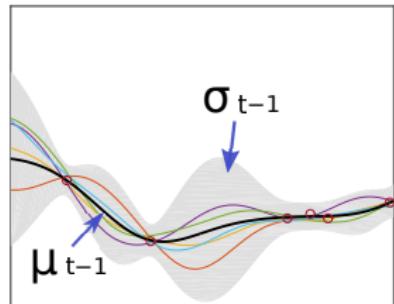
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(Srinivas et al., 2010)



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## Existing acquisition functions

Upper Confidence Bound (GP-UCB) (Srinivas et al., 2010)

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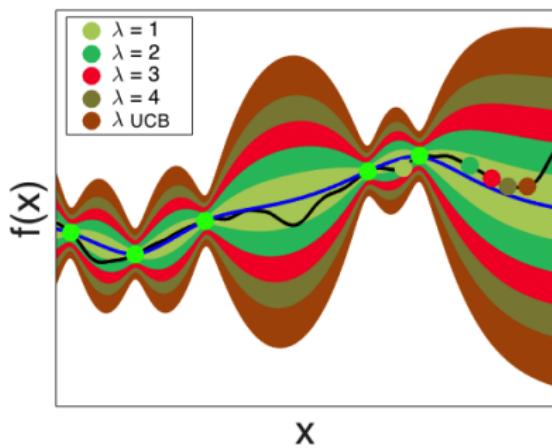
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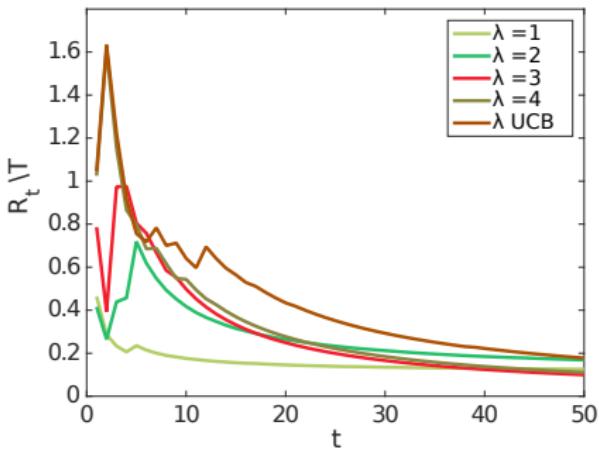
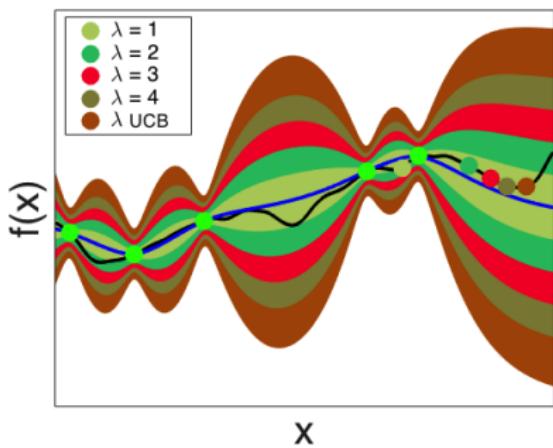


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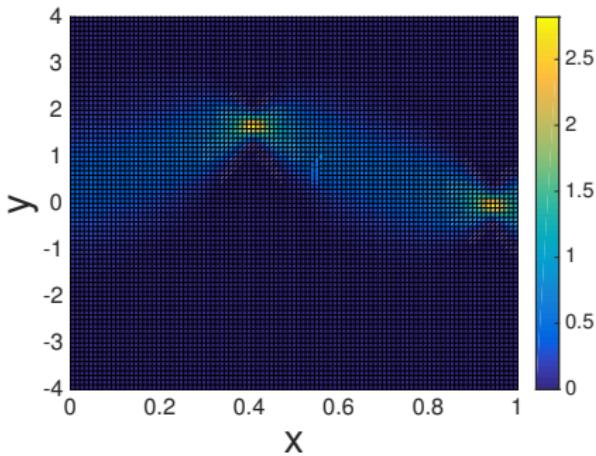
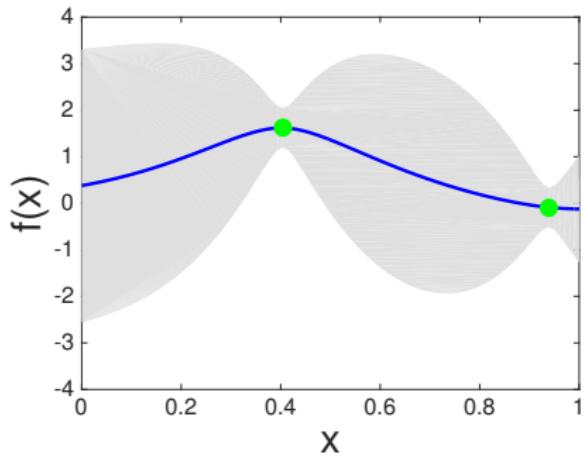
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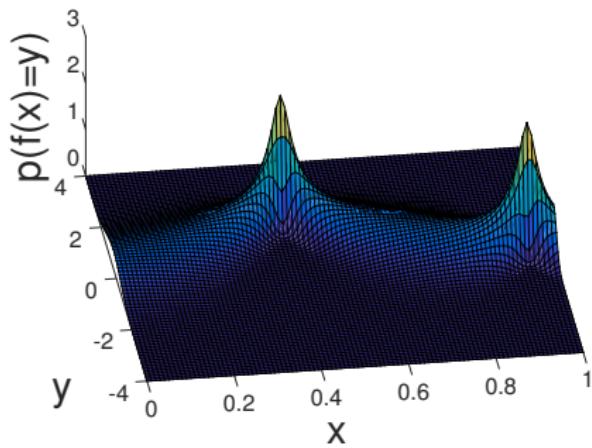
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- Approximate the joint Gaussian with independent Gaussians

$$g(w) = 1 - \Pr[f(\mathbf{x}) \leq w, \forall \mathbf{x} \in \mathfrak{X}] \approx 1 - \prod_{\mathbf{x} \in \mathfrak{X}} \Phi\left(\frac{w - \mu(\mathbf{x})}{\sigma(\mathbf{x})}\right)$$

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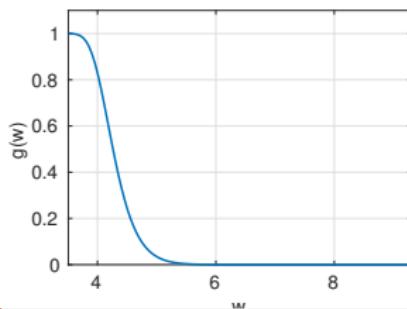
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- Integrate numerically (ESTn) or approximately (ESTa)



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$$\Pr[f(\mathbf{x}) \text{ is the maximum} | \hat{m}] \approx Q\left(\frac{\hat{m} - \mu(\mathbf{x})}{\sigma(\mathbf{x})}\right) \prod_{\mathbf{x}' \neq \mathbf{x}} \Phi\left(\frac{\hat{m} - \mu(\mathbf{x}')}{\sigma(\mathbf{x}')}\right)$$

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$$\arg \max_{\mathbf{x} \in \mathfrak{X}} \Pr[f(\mathbf{x}) \text{ is the maximum} | \hat{m}] = \arg \min_{\mathbf{x} \in \mathfrak{X}} \frac{\hat{m} - \mu(\mathbf{x})}{\sigma(\mathbf{x})}$$

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$$\Pr[\mathbf{x} = \arg \max f(\mathbf{x}) | \hat{m}]_{\theta = \hat{m}}$$

PI

$$\text{PI}(\mathbf{x}) = \Pr[f(\mathbf{x}) > \theta]$$



# Connections to GP-UCB and PI

## GP-UCB

$$\text{UCB}(\mathbf{x}) = \mu(\mathbf{x}) + \lambda\sigma(\mathbf{x})$$

$$\lambda = \min_{\mathbf{x} \in \mathfrak{X}} \frac{\hat{m} - \mu(\mathbf{x})}{\sigma(\mathbf{x})}$$


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$$\text{PI}(\mathbf{x}) = \Pr[f(\mathbf{x}) > \theta]$$

# Connections to GP-UCB and PI

- At round  $t$ , pick the input that is most likely to reach a target value.

$$\hat{m}_t = \begin{cases} \max_{\mathbf{x} \in \mathfrak{X}} \mu_{t-1}(\mathbf{x}) + \lambda_t \sigma_{t-1}(\mathbf{x}) & \text{GP-UCB} \\ \theta_t & \text{PI} \\ \mathbb{E}[\max_{\mathbf{x} \in \mathfrak{X}} f(\mathbf{x})] & \text{EST} \end{cases}$$
$$\mathbf{x}_t \leftarrow \arg \min_{\mathbf{x} \in \mathfrak{X}} \frac{\hat{m}_t - \mu_{t-1}(\mathbf{x})}{\sigma_{t-1}(\mathbf{x})}$$

# Regret bounds

Theorem (Regret bounds for EST)

Assume  $\hat{m}_t \geq \max_{\mathbf{x} \in \mathfrak{X}} f(\mathbf{x})$ ,  $\forall t \in [1, T]$ . Then,

$$\mathbb{E}[R_T] \leq \nu_{t^*} \sqrt{CT\gamma_T}.$$

With probability at least  $1 - \delta$ ,

$$R_T \leq (\nu_{t^*} + \zeta_T) \sqrt{CT\gamma_T},$$

$$C = \frac{2}{\log(1+\sigma^{-2})}, \quad \nu_t \triangleq \min_{\mathbf{x} \in \mathfrak{X}} \frac{\hat{m}_t - \mu_{t-1}(\mathbf{x})}{\sigma_{t-1}(\mathbf{x})}, \quad t^* = \arg \max_t \nu_t.$$
$$k(\mathbf{x}, \mathbf{x}') \leq 1, \quad \gamma_T = \max_{A \subseteq \mathfrak{X}, |A| \leq T} I(\mathbf{y}_A, \mathbf{f}_A), \quad \zeta_T = (2 \log(\frac{T}{2\delta}))^{\frac{1}{2}}.$$

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# Estimating an upper bound on the function maximum

Slepian's Comparison Lemma (Slepian, 1962; Massart, 2007)

Let  $\mathbf{u}, \mathbf{v} \in \mathbb{R}^n$  be two multivariate Gaussian random vectors with the same mean and variance, such that

$$\mathbb{E}[\mathbf{v}_i \mathbf{v}_j] \leq \mathbb{E}[\mathbf{u}_i \mathbf{u}_j], \forall i, j.$$

Then,

$$\mathbb{E}\left[\sup_{i \in [1, n]} \mathbf{v}_i\right] \geq \mathbb{E}\left[\sup_{i \in [1, n]} \mathbf{u}_i\right].$$

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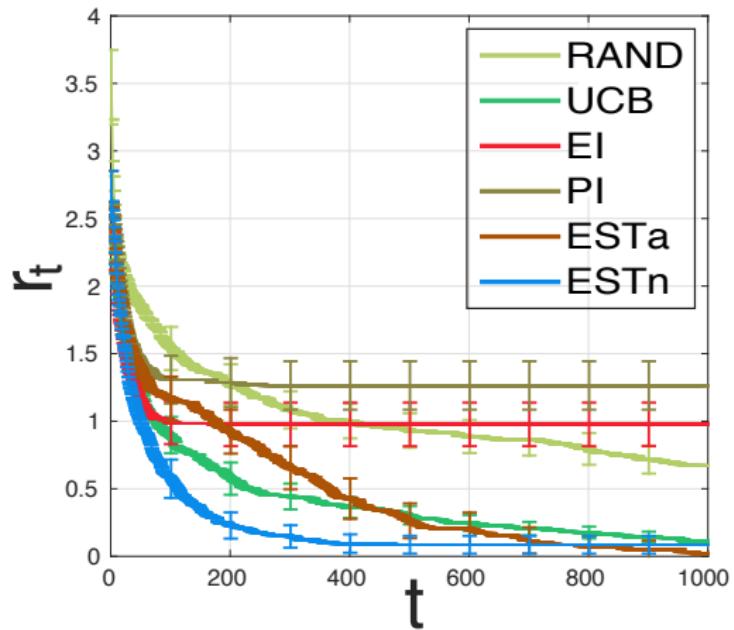
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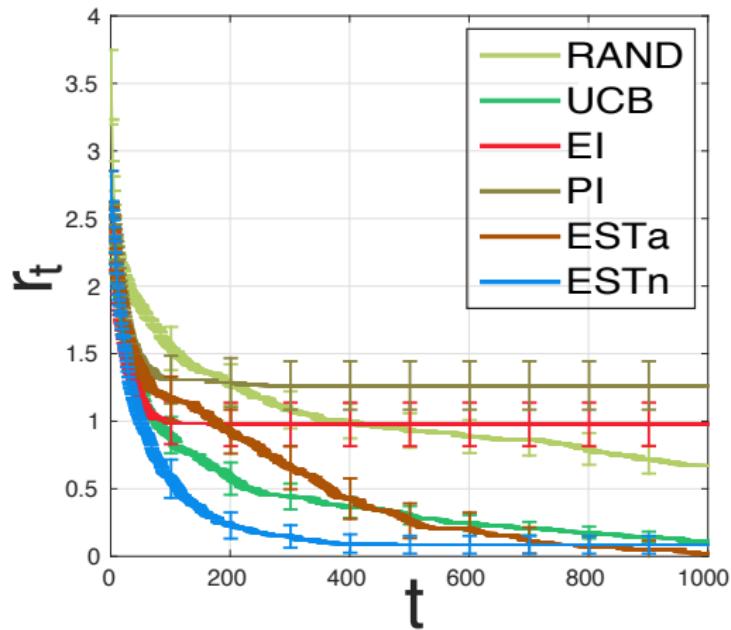
**Ignoring positive covariance gives higher expected maximum.**

# Experiments

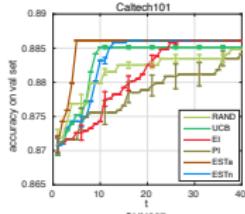


# Experiments

Robotics



Vision



More results at Session 2 Poster 47

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